



## Graph kernels

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# Motivation

## Structural Pattern Recognition

- 😊 Rich description of objects
- 😞 Poor properties of graph's space does not allow to readily generalize/combine sets of graphs

## Statistical Pattern Recognition

- 😞 Global description of objects
- 😊 Numerical spaces with many mathematical properties (metric, vector space, ...).

## Motivation

Analyse large families of structural and numerical objects using a **unified** framework based on pairwise similarity.



# Kernels : Definition

- A kernel  $k$  is a **symmetric** similarity measure on a set  $\chi$

$$\forall (x, y) \in \chi^2, k(x, y) = k(y, x)$$

- $k$  is said to be **definite positive** (d.p.) iff  $k$  is symmetric and iff:

$$\left. \begin{array}{l} \forall (x_1, \dots, x_n) \in \chi^n \\ \forall (c_1, \dots, c_n) \in \mathbb{R}^n \end{array} \right\} \sum_{i=1}^n \sum_{j=1}^n c_i c_j k(x_i, x_j) \geq 0$$

- $K = (k(x_i, x_j))_{(i,j) \in \{1, \dots, n\}}$  is the Gramm matrix of  $k$ .  $k$  is d.p. iff:

$$\forall c \in \mathbb{R}^n - \{0\}, c^t K c \geq 0$$



# Kernels and scalar products

Aronszajn 1950 :

A kernel  $k$  is d.p. on a space  $\chi$   
if and only if  
it exists

- one Hilbert space  $\mathcal{H}$  and
- a function  $\varphi : \chi \rightarrow \mathcal{H}$

such that:

$$k(x, y) = \langle \varphi(x), \varphi(y) \rangle$$



# Outline

## Kernel and structured data

The kernel trick provides an implicit embedding whose metric is defined from our similarity criterion (the kernel).



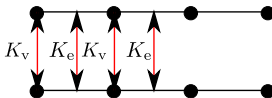
# Walk kernels

- Walks: Let  $G = (V, E)$ .  $W = (v_1, \dots, v_n)$  is a walk iff  $(v_i, v_{i+1}) \in E, \forall i \in \{1, \dots, n-1\}$ .



- Kernel between walks

$$K(h, h') = \begin{cases} 0 & \text{if } |h| \neq |h'| \text{ and} \\ K_v(v_1, v'_1) \cdot \prod_{i=1}^{|h|} K_e(e_i, e'_i) K_v(v_{i+1}, v'_{i+1}) & \text{otherwise} \end{cases}$$



- Walk kernels :

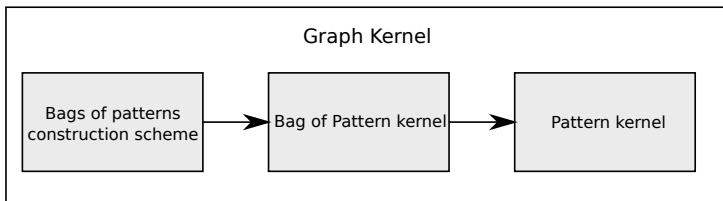
$$K(G_1, G_2) = \sum_{h \in \mathcal{W}(G_1)} \sum_{h' \in \mathcal{W}(G_2)} K(h, h') \lambda_{G_1}(h) \lambda_{G_2}(h')$$



# Finite Bag kernels

$$\left. \begin{array}{l} G \rightarrow B(G) \\ G' \rightarrow B(G') \end{array} \right\} K(G, G') = K(B(G), B(G'))$$

Three independent step to design a graph kernel.





## Questions :

Which type of graph best capture object's properties ?

Shape recognition:

- Shape described by skeletons encoded by graphs  $G = (V, E, \omega)$ .
  - $V$ :
    - extremities/intersection of branches or
    - abrupt changes of the radius along a branch.
  - $E$ :
    - branches of the skeleton.
    - Each edge is weighted by a function  $\omega$  encoding the length of the boundary which contributed to the branch [Torsello04].



Chemoinformatic:  $G = (V, E, \mu, \nu)$

- $V$  set of atoms,  $\mu$  atom's type,
- $E$  set of bounds,  $\nu$  bound's type.





## Questions :

- Which type of graph best capture object's properties ?
- Which pattern should we choose ?
  - Paths,
  - Sub trees,
  - Sub graphs.
  - Sub combinatorial maps,...
- How to build a bag which minimizes the loss of information ?
  - All patterns up to a given size ?
  - More relevant patterns ?
    - Shape recognition: A priori information  $\rightarrow$  covering problem
    - Chemoinformatics: Multiple kernel learning with one kernel per pattern.
- How to define a kernel between bags

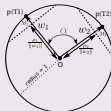
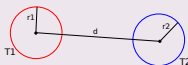


# Bag of paths kernels shape recognition

Haussler99

$$K_{\text{mean}}(T_1, T_2) = \frac{1}{|T_1|} \frac{1}{|T_2|} \sum_{t \in T_1} \sum_{t' \in T_2} K_{\text{pattern}}(t, t'),$$

## More complex kernels



(Desobry 2005)

$$K'(x, y) = \frac{K(x, y)}{\sqrt{K(x, x)K(y, y)}}$$

$$K'(x, x) = \|\varphi'(x)\|^2 = 1$$

Normalized kernel

## Weighted mean kernel

$$K_{\text{weighted}}(T_1, T_2) = \frac{1}{|T_1|} \frac{1}{|T_2|} \sum_{t \in T_1} \sum_{t' \in T_2} \lambda_{T_1}(t) \lambda_{T_2}(t') K_{\text{pattern}}(t, t'),$$

$$\lambda_{T_i}(t) = \langle \varphi(t), \mu_{T_i} \rangle^d$$



## Basic

$$K_{\text{mean}}(G_1, G_2) = \sum_{t \in T(G_1) \cap T(G_2)} K(f_t(G_1), f_t(G_2)),$$

## Basic MKL

$$K_{\text{BMKL}}(G_1, G_2) = \sum_{t \in T(G_1) \cap T(G_2)} d_t K(f_t(G_1), f_t(G_2)),$$

## Infinite MKL

$$K_{\text{IMKL}}(G_1, G_2) = \sum_{t \in \mathcal{T}} \sum_{t' \in \mathcal{T}, t' \leq t} d_{t,t'} K(f_t(G_1), f_{t'}(G_2)),$$

where  $\mathcal{T} = T(G_1) \cup T(G_2)$



# Pattern kernels

## How to compare patterns

- Classical approach:

$$K_{\text{classic}}(t, t') = \begin{cases} 0 & \text{if } t \not\sim t', \\ \sum_{\varphi \in \text{Isom}(t, t')} \left( \prod_{i=1}^{|V|} K_v(\mu(v_i), \varphi(\mu(v'_i))) \right) \\ \left( \prod_{i=1}^{|E|} K_e(\nu(e_i), \nu(e'_i)) \right) \end{cases}$$

- Pb: Similar but not identical patterns are not comparable.
- Solutions :
  - Shape recognition : Use rewritings
  - Chemoinformatics : Use edit distance.



## Conclusion

- Our aim : Study properties of structure space and combine structural pattern recognition and machine learning/optimisation methods.

Thank you for your attention !

Questions ?



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- Next talk.